

Optimal polynomial meshes exist on any multivariate convex domain

Andriy Prymak
(joint work with Feng Dai)

University of Manitoba

Optimal polynomial meshes

$\|f\|_E := \max_{\mathbf{x} \in E} |f(\mathbf{x})|$, where $E \subset \mathbb{R}^d$ is a compact set and $f \in C(E)$.
 \mathcal{P}_n^d — real algebraic polynomials in d variables of total degree at most n .
Note $\dim \mathcal{P}_n^d \approx n^d$.

A compact $\Omega \subset \mathbb{R}^d$ possesses *optimal polynomial meshes* if
 $\exists \{Y_n\}_{n \geq 1}$, $Y_n \subset \Omega$, $\#Y_n \leq C_1 n^d$ such that

$$\|P\|_\Omega \leq C_2 \|P\|_{Y_n} \quad \forall P \in \mathcal{P}_n^d, \quad (1)$$

where C_1, C_2 depend only on Ω .

Applications in: discrete least squares approximation, cubature formulas, scattered data interpolation, study of discrete Fekete and Leja type sets.

A constructive proof of existence usually involves some polynomial inequalities which are of independent interest.

Example: segment

$$|P'(x)| \leq \min\left\{n^2, \frac{n}{\sqrt{1-x^2}}\right\} \|P\|_{[-1,1]} \quad \forall P \in \mathcal{P}_n^1$$

For Chebyshev partition $\{\cos \frac{k\pi}{N}\}_{k=0}^N$, $N = \ell n$, this Bernstein-Markov factor behaves as $\frac{o(\ell)}{|I|}$ when $x \in I$, $\ell \rightarrow \infty$, where I is any interval of the partition.

$$\max_{x \in I} |P'(x)| |I| \leq \frac{1}{2} \|P\|_{[-1,1]}$$

From each I select a point to include into Y_n . Then for any $P \in \mathcal{P}_n^1$ we can find z with $|P(z)| = \|P\|_{[-1,1]}$ so if $z \in I$ and $y \in I \cap Y_n$, by MVT

$$\|P\|_{Y_n} \geq |P(y)| \geq \|P\|_{[-1,1]} - \max_{x \in I} |P'(x)| |I| \geq \frac{1}{2} \|P\|_{[-1,1]}.$$

History of the problem

2012 Bloom, Bos, Calvi, Levenberg: *nearly* optimal meshes, i.e. those satisfying (1) with $\#Y_n \leq C(n \log n)^d$, exist for any compact $\Omega \subset \mathbb{R}^d$. (Fekete points used, essentially non-constructive proof.)

Existence (constructive) of optimal polynomial meshes

2011, 2013 Kroo: convex polytopes, C^α star-like domains with $\alpha > 2 - \frac{2}{d}$.

Conjecture: any convex body in \mathbb{R}^d , $d \geq 2$.

2016 Piazzon: certain extension of C^2 domains.

2019 Kroo: any convex body in \mathbb{R}^2 using a new tangential Bernstein type inequality.

2021 P.: alternative proof for any convex body in \mathbb{R}^2 via a connection between the Christoffel functions, positive quadrature formulas and polynomial meshes established in the paper [2] of Bos and Vianello (2019).

We confirm Kroo's conjecture for $d \geq 3$.

Theorem

For any convex body $\Omega \subset \mathbb{R}^d$, there exists $\{Y_n\}_{n \geq 1}$, $Y_n \subset \Omega$, $\#Y_n \leq C(d)n^d$ such that

$$\|P\|_{\Omega} \leq 2\|P\|_{Y_n} \quad \forall P \in \mathcal{P}_n^d. \quad (2)$$

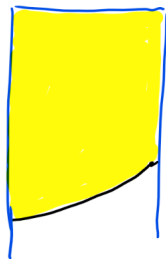
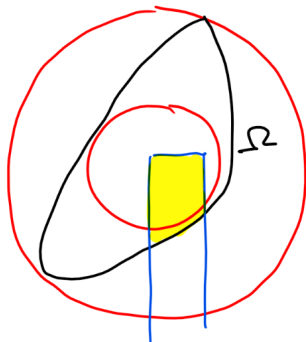
ε -version is also valid: 2 can be replaced with $1 + \varepsilon$ and $C(d)$ with $C(d, \varepsilon)$.

John's theorem, graph-type domains

Optimal meshes are invariant under affine transforms, so John's theorem on inscribed ellipsoid of the largest volume allows to assume

$$B(\mathbf{0}, 1) \subset \Omega \subset B(\mathbf{0}, d) \quad (3)$$

and represent Ω as the union of graph-type domains with good parameters.

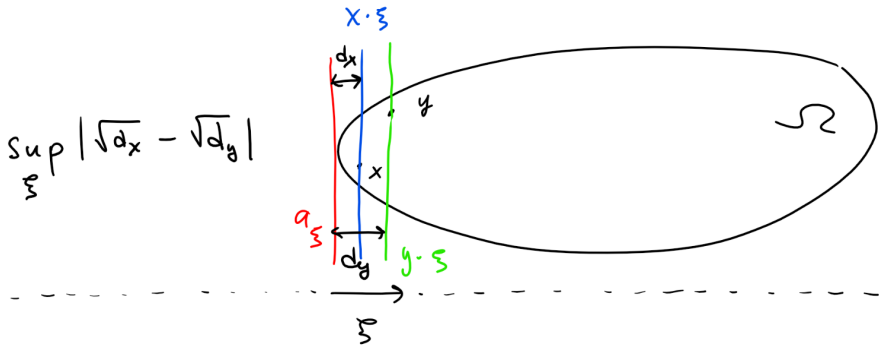


Dubiner's metric

Let $\Omega \subset \mathbb{R}^d$ be a convex body. For any $\mathbf{x}, \mathbf{y} \in \Omega$, define

$$\rho(\mathbf{x}, \mathbf{y}) := \rho_{\Omega}(\mathbf{x}, \mathbf{y}) := \max_{\xi \in \mathbb{S}^{d-1}} \left| \sqrt{\mathbf{x} \cdot \xi - a_{\xi}} - \sqrt{\mathbf{y} \cdot \xi - a_{\xi}} \right|, \quad (4)$$

where $a_{\xi} := \min_{\mathbf{z} \in \Omega} \mathbf{z} \cdot \xi$, and \mathbb{S}^{d-1} denotes the unit sphere of \mathbb{R}^d .

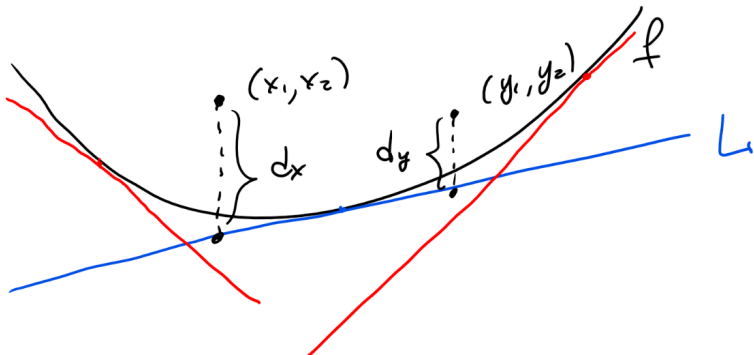


Equivalent metric for special subdomains

When $d = 2$ for a special subdomain G which essentially the epigraph of f an equivalent metric will be

$$\rho_G((x_1, x_2), (y_1, y_2)) = \max_L |\sqrt{x_2 - L(x_1)} - \sqrt{y_2 - L(y_1)}|$$

with maximum over all supporting lines L to f .



Construction of the mesh

There exists a small $c_d > 0$ such that for arbitrary $0 < \eta \leq c_d$ one can take Λ_n as any η/n -separated set which is c_d/n -covering w.r.t. ρ , i.e.:

(separation) $\forall x, y \in \Lambda_n, x \neq y: \rho(x, y) \geq \eta/n$;

(covering) $\forall z \in \Omega \exists x \in \Lambda_n: \rho(z, x) \leq c_d/n$.

When $\eta = c_d$, the above conditions mean that Λ_n is a maximal c_d/n -separated set in Ω w.r.t. ρ . Choosing $\eta < c_d$ allows more flexibility in construction of Λ_n .

Variation of polynomials

We obtain the estimate (2) as an immediate consequence of the covering condition and the following:

Theorem

Let $\Omega \subset \mathbb{R}^d$ be a convex body satisfying (3). There exists $C_*(d) > 0$ such that for any $Q \in \mathcal{P}_n^d$ with $\|Q\|_\Omega \leq 1$, we have

$$|Q(\mathbf{x}) - Q(\mathbf{y})| \leq C_*(d)n\rho(\mathbf{x}, \mathbf{y}) \quad \text{whenever } \mathbf{x}, \mathbf{y} \in \Omega. \quad (5)$$

The proof of Theorem 2 is essentially two-dimensional which is due to the fact that any supporting line to a 2-dimensional section of Ω can be extended to a supporting hyperplane for Ω .

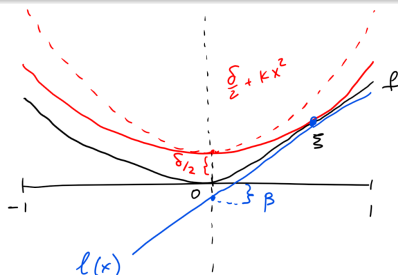
Key planar lemma

Lemma

If $f : [-1, 1] \rightarrow [0, \infty)$ is convex with $f(0) = 0$ and $\max_{x \in [-1, 1]} f(x) > \frac{\delta}{2}$, then there exist $k > 0$, $\xi \in [-1, 1] \setminus \{0\}$, and $l(x) := \alpha x - \beta$ satisfying:

$$0 < |\alpha| \leq \frac{1}{3}, \quad 0 \leq \beta \leq \frac{1}{3}, \quad l(\xi) = f(\xi), \quad l'(\xi) = f'_-(\xi),$$

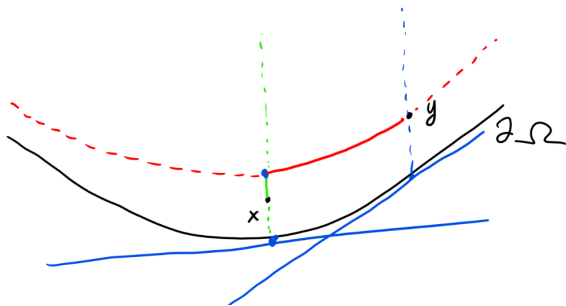
$$f(x) \leq \frac{\delta}{2} + kx^2 \quad \forall x \in [-1, 1], \quad \frac{\sqrt{\delta + \beta}}{|\alpha|} < \frac{1}{\sqrt{k}}.$$



Key planar lemma: consequences

We find that it suffices to use $\rho(\mathbf{x}, \mathbf{y})$ with the maximum in (4) being taken over only two specific directions which are inward normal vectors at two boundary points of Ω . ($x = 0$ and $x = \xi$)

This allows us to explicitly construct a parallelogram in G containing both \mathbf{x} and \mathbf{y} , as well as certain families of parabolas and straight segments in G along which the standard one-dimensional Bernstein inequality can be applied to derive (5).



Multivariate fast decreasing polynomials

To complete the proof, it suffices to show $\#Y_n \leq \dim \mathcal{P}_{C^*n}^d$ for some large $C^* = C^*(d)$. Indeed, if this were not true, then one can get a contradiction using linear dependence of the “fast decreasing” polynomials provided by the following theorem for each $\mathbf{x} \in Y_n$.

Theorem

Let $\Omega \subset \mathbb{R}^d$ be a convex body satisfying (3). For any $\mathbf{x} \in \Omega$ and $n \in \mathbb{N}$, there exists a polynomial $P \in \mathcal{P}_n^d$ such that $P(\mathbf{x}) = 1$ and

$$0 \leq P(\mathbf{z}) \leq C \exp(-c\sqrt{n\rho(\mathbf{x}, \mathbf{z})}) \quad \text{for any } \mathbf{z} \in \Omega, \quad (6)$$

where $C > 1$ and $c \in (0, 1)$ are constants depending only on d .

Doubling property

An important ingredient for the proof of this theorem and for obtaining the above mentioned contradiction is the doubling property of ρ .

Theorem

Let $\Omega \subset \mathbb{R}^d$ be a convex body satisfying (3). For any $\mathbf{x} \in \Omega$ and $h > 0$

$$|B_\rho(\mathbf{x}, 2h)| \leq 4^d |B_\rho(\mathbf{x}, h)|. \quad (7)$$

The proof is essentially one-dimensional by considering strips

$$S(\Omega, \mathbf{x}, \boldsymbol{\xi}, h) := \left\{ \mathbf{y} \in \Omega : \left| \sqrt{\mathbf{x} \cdot \boldsymbol{\xi} - a_\xi} - \sqrt{\mathbf{y} \cdot \boldsymbol{\xi} - a_\xi} \right| \leq h \right\}$$

and showing

$$S(\Omega, \mathbf{x}, \boldsymbol{\xi}, 2h) \subset \varphi \left(S(\Omega, \mathbf{x}, \boldsymbol{\xi}, h) \right), \quad \mathbf{x} \in \Omega, \quad \boldsymbol{\xi} \in \mathbb{S}^{d-1},$$

where $\varphi(\mathbf{z}) := \mathbf{x} + 4(\mathbf{z} - \mathbf{x})$.

References

- [1] T. Bloom, L. P. Bos, J.-P. Calvi, and N. Levenberg, *Polynomial interpolation and approximation in \mathbb{C}^d* , Ann. Polon. Math. **106** (2012), 53–81.
- [2] Len Bos and Marco Vianello, *Tchakaloff polynomial meshes*, Ann. Polon. Math. **122** (2019), no. 3, 221–231.
- [3] Moshe Dubiner, *The theory of multi-dimensional polynomial approximation*, J. Anal. Math. **67** (1995), 39–116.
- [4] K. G. Ivanov and V. Totik, *Fast decreasing polynomials*, Constr. Approx. **6** (1990), no. 1, 1–20.
- [5] András Kroó, *On optimal polynomial meshes*, J. Approx. Theory **163** (2011), no. 9, 1107–1124.
- [6] ———, *Bernstein type inequalities on star-like domains in \mathbb{R}^d with application to norming sets*, Bull. Math. Sci. **3** (2013), no. 3, 349–361.
- [7] A. Kroó, *Multivariate fast decreasing polynomials*, Acta Math. Hungar. **149** (2016), no. 1, 101–119.
- [8] András Kroó, *On the existence of optimal meshes in every convex domain on the plane*, J. Approx. Theory **238** (2019), 26–37.
- [9] Federico Piazzon, *Optimal polynomial admissible meshes on some classes of compact subsets of \mathbb{R}^d* , J. Approx. Theory **207** (2016), 241–264.
- [10] A. Prymak, *Geometric computation of Christoffel functions on planar convex domains*, J. Approx. Theory **268** (2021), Paper No. 105603, 13.

Thank you!